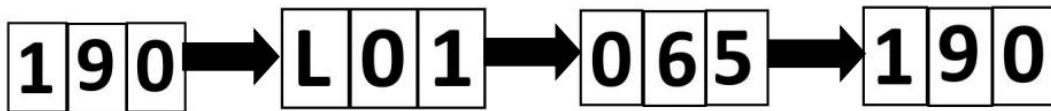


Mainboard parameter setting operation process

1. Operation process:

- Long press the menu key to enter menu options
- Press the +/- key to select the corresponding menu options
- Press menu key to enter parameter adjustment options, and press +/- to adjust parameters
- After setting the parameters, press the "ok" button to exit

2. The digital tube corresponds to the display state



Function	Subtitle menu	Digital menu	Parameter set	Default Paeters	Parameter specification
Adjust the opening speed	L-1	L01	20-95	70	The higher the value, the faster the barrier opens
Adjust the closing speed	L-2	L02	20-95	70	The higher the value, the faster the barrier close
Stability of the barrier in place	L-3	L03	8-15	10	
Sensitivity adjustment of reaction time to prevent car crash	L-4	L04	15-30	25	
Motor force value adjustment/menu display form setting	L-5	L05	70-90	70	The greater the value, the greater the motor force/When the parameter is an even number, the digital tube is an alphabetic menu and a singular number menu
Adjust the horizontal position of the barrier	L-6	L06	3-90	10	
Test mode selection	L-7	L07	0-6	0/1	0(manual) 1(automatic) The following 1-5 is the interval time of automatic operation, 1 is the fastest, 5 is the slowest, and 6 is the half-stroke operation of the barrier
Opening memory function Settings	L-8	L08	0-1	0/1	0 (no memory) 1 (with memory) 4 (peak mode, when the barrier is fully open, press the stop button of the remote control to enable this function, and press the close button of the remote control to cancel)

Adjust the vertical position of barrier	L-9	L09	3-90	10	
The first section opens the barrier to decelerate the stroke adjustment	L-L	L10	20-90	45	
The first section close the barrier to decelerate the stroke adjustment	L-b	L11	20-90	45	
Adjust the force of anti-collision	L-c	L12	15-100	40	Cancel the anti-crash function if the value exceeds 100
Barrier movement positive and negative operation Settings	L-d	L13	0-3	0/1/2/3	0: motor positive, reducer forward 1: Motor negative, reducer forward transmission 2: The motor is negative, and the reducer is backward 3: motor positive reducer is backward
Starting motor force value of barrier	L-E	L14	20-40	30	
Added learning remote control function	L-F	L15	0-255	0	
The second section opens the barrier to decelerate the stroke adjustment	L-H	L16	1-10	0	For 0.3S open speed, high speed barrier
The second section close the barrier to decelerate the stroke adjustment	L-P	L17	0-255	0	For 0.3S open speed, high speed barrier
Regulation of traffic light/tape/detection status mode	L-18	L18	0-2	0	0 is the green space mode, 1 is the test state mode of the in-place parts, and 2 is the tri-color lamp belt mode (external relay is required).
Loop sensor delay close barrier time adjustment	L-19	L19	1-255	000	The value represents the time of delayed falling after passing the loop, 000 represents the disuse of this function, which needs to be equipped with a loop sensor
Auto close time adjustment	L-20	L20	1-255	000	The value represents the time of delayed falling, 000 represents the disuse of this function